|  | Gearbox<br>Type CE | CE001-e |
|--|--------------------|---------|
|  | I                  |         |

# USE INSTRUCTIONS

For two speed gearbox Œ series 23.12..... 23.14.....

Before the setting at work, follow carefully this guide !



It is allow only to experts, who examined the instructions, to work on the gearbox

Responsability and warranty are excluded when:

- Warning and use instructions are not followed
- The gearbox is set at work in a wrong way The gearbox maintenance is not followed correctly
- Function modifications of every kind are introduced without the manufacturer authorization
- Original spare parts are not used

### NOTE:



- The sign points out operations of special care
- A wrong process can cause damage to the gear box
- Wrong process can endanger the safety of the operator

| Edition   | Revision | RIPAHII s.p.a.      |       |  |
|-----------|----------|---------------------|-------|--|
| July 1999 |          | <br>Donato Milanese | ITALY |  |

| INDEX |                       | Gearbox<br>Type Œ | <br>Œ001-e |
|-------|-----------------------|-------------------|------------|
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| 1.2   | Variations for oil fo | rced lubrication  | 3          |
| 1.3   | Outlet shaft bearing  |                   | 4          |
| 2.    | Setting at work       |                   | 5          |
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| 2.4   | Technical data        |                   | 7          |
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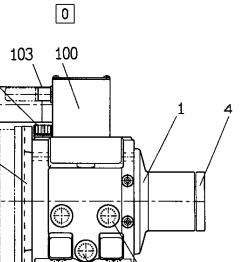
Gearbox structure

Gearbox type Œ

Œ001-e

### Gearbox structure

1.1 Version for splash lubrication



Code:

0

0

4 = Output shaft 1

4a = Output shaft 2

1 = Casing

3 = Flange

100 = Actuator and data number plate

103 = Electrical connector

★F = Oil loading plug and vent valve

\*C = Oil level warning light

\*A = Oil discharge

M = Motor

Code:



The motor(M) is fixed on the gearbox casing (1) throught the interposition of the flange(3); for some versions, this constitutes only a center square element, therefore is not visible. The casing (1) is normally fixed on the machine. On the output shaft (4) o (4a) is normally fixed the pulley for the motion transfer. The electrical connection has to be made on the connector (103)

The indicated function with(\*), must be made only for OPP orizontal assembly position. For other assembly position see chapter 2.7.



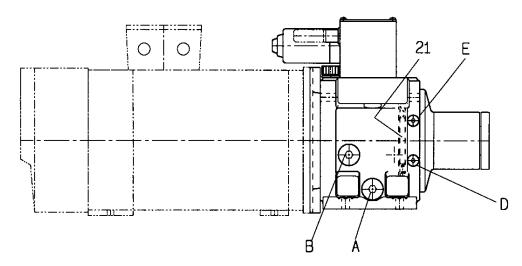
1. Gearbox structure

Gearbox Type Œ

Œ001-e

1.2 Variations for forced lubrication





Code:



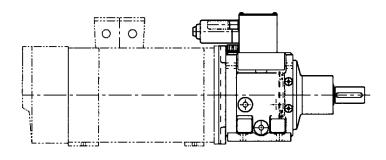
21 = Distributor (inside)

\*B =Oil feedeng choke for elements lubrication in inlet

**★**E = Oil feeding for central unit lubrication

\*D = Oil feedeng for elements lubrication in outlet

\*A = Oil discharge



Code:



The indicated function with(\*), must be made only for OPP horizontal assembly positions. For other assembly positions see chapter 2.7

| <del></del> |  |
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# 1. Gearbox structure

| Geart | юх |
|-------|----|
| Type  | Œ  |

Œ001-e

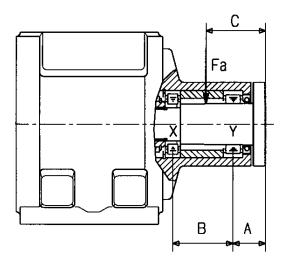
# 1.3 Output shaft bearings

In the table 1 are indicated the bearings mounted on the output shaft with the related loading capacity values.

These elements, added to the data on table 2, allow to determinate the bearings life in function of the resulting load Fa of its position and of the r.p.m.

Table 1

| Gearboxes  | Bearings X |                                 | Bearings Y |                                 |
|------------|------------|---------------------------------|------------|---------------------------------|
| Ocal buxes | Туре       | Basic load<br>ratings dynamic N | Туре       | Basic load<br>ratings dynamic N |
| Œ 12       | NUP208ECP  | 53900                           | NU2208E0P  | 70400                           |
| Œ 14       | NUP211EOP  | 84200                           | NU2211E0P  | 99000                           |



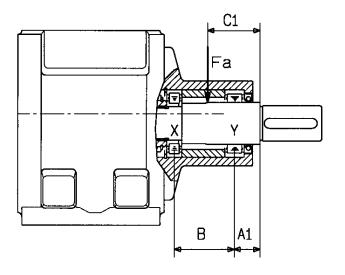


Table 2

| mm        | Œ12   | Œ14   |
|-----------|-------|-------|
| A         | 39    | 47.5  |
| <b>A1</b> | 24    | 27.5  |
| В         | 71.5  | 87    |
| С         | 48-70 | 57-87 |
| C1        | 33-55 | 37-67 |

Fa = Resulting radial force in the other words belt-pull

C e C1 indicate the suggested position of Fa force

|           | ) MIPADI s.p.a.     |       | Page  | 4/34  |
|-----------|---------------------|-------|-------|-------|
|           | S.p.a.              |       | , age | ., ., |
| July 1998 | San Donato Milanese | ITALY |       |       |

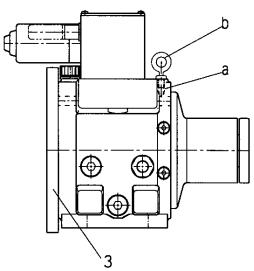
| 2. | Setting | at | work |
|----|---------|----|------|
|----|---------|----|------|

Gearbox Type CE

Œ001-e

## 2. Setting at work

# 2.1 Advices for the tranportation



a = Hole for eyebolt

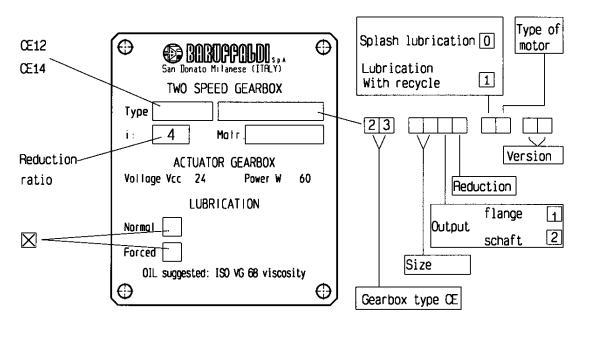
b = Eyebolt (excluded for the supply)

3 = Flange

Table 3

| Gearboxes | Dimension hole<br>for eyebolt | Weight of the<br>gearbox Kg. |
|-----------|-------------------------------|------------------------------|
| Œ 12      | M 10                          | 47                           |
| Œ 14      | M 12                          | 90                           |

### 2.2 Data plate



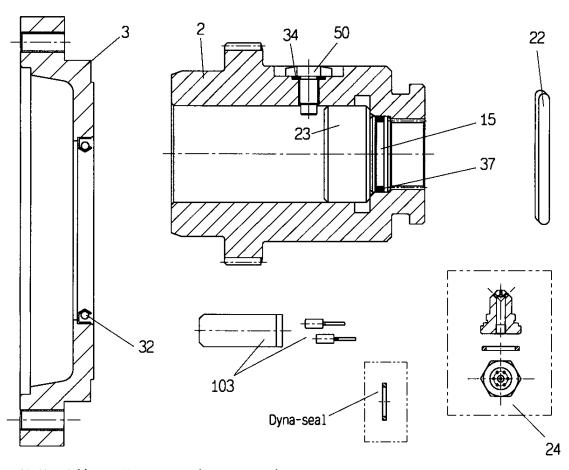
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### 2.3 Conditions at delivery

Further to the instruction manual the gearbox is delivered with:

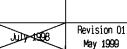
- Flange(3) corresponding to the ordered motor complete with rotating seal (32)
- Pinion (2) corresponding to the ordered motor
- Locking screw (50)
- 0-ring (34)
- Seeger ring (40)
- Plug (15)
- 0-ring (37)
- insert for balancing (22)
- Electrical connector (103) complete with the plug and corresponding pins
- Choke (24) complete with washer:it is delivered only with version prepared for forced lubrication
- Spacer only if required
- Washer (Dyna-seal): only for special versions (see 2.8.2 pic. 8a)



At the delivery the gearbox is engaged with the second speed



The gearbox is delivered without oil: before the put in function provide to fill it or to install the forced lubrication as described in chapter 3.1.





Gearbox Type CE

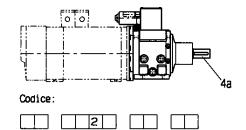
Œ001-e

### 2.4 Technical data

|  | <u>~</u> | Œ 12            |         | Œ 14            |  |
|--|----------|-----------------|---------|-----------------|--|
| Size                                   | (i = 4)  | 12<br>  (i = 5) | (i = 4) | 14<br>  (i = 5) |  |
| Nominal rating<br>KW                   | 22       | 22              | 50      | 50              |  |
| Nominal torque inlet                   | 140      | 140             | 325     | 280             |  |
| Max torque (S6) inlet<br>Nm            | 160      | 160             | 400     | 325             |  |
| Nominal torque (S1)<br>outlet = 1:1 Nm | 140      | 140             | 325     | 325             |  |
| Nominal torque i=4                     | 560      | X               | 1300    |                 |  |
| outlet Nm i=5                          |          | 700             | X       | 1400            |  |
| X Max number of revolution inlet (RPM) | 9000     | 9000            | 7000    | 7000            |  |
| Moment of inertia i = 1                | 215      | 215             | 750     | 750             |  |
| of the masses i = 4                    | 32       |                 | 115     |                 |  |
| inlet Kgcm2 i = 8                      | 5        |                 |         |                 |  |

 $\times$  See chapter 2.7 ( assembly position and lubrications )





The outolet shaft (4a) of the gearboxes type is balanced with half key

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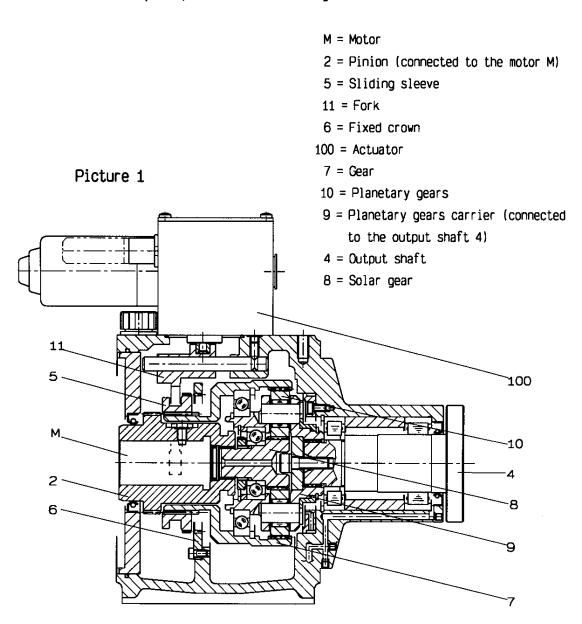
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Gearbox Type CE

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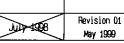
### 2.5 Operating running condition

The actuator (100), throught the fork (11), has the function to move the sliding sleeve(5) to engage or the pinion (2) or the fixed crown (6). The ratio is fixed by the position of the sliding sleeve.



## 2.5.1 Gearbox in neutral position pic.1

The sliding sleeve in cental position, disengaged either from the pinion(2) or from the crown(6). The motor (M), throught the pinion (2), trasmits the rotation to the solar gear (8) which throught the planetaries(10), brings in rotation the gear (7) while the planetary gears carrier (9) and the output shaft (4) are non interested in the rotation except a limited dragging due to the frictions.





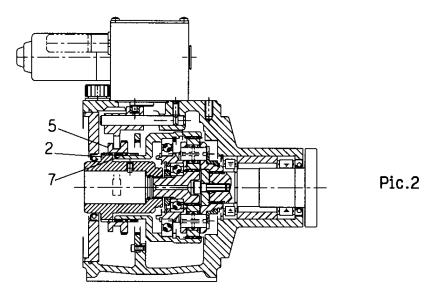
Gearbox Type CE

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### 2.5.2 Gearbox in ratio 1:1 (pic2)

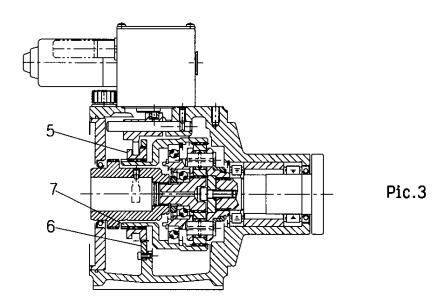
Sliding sleeve (5) engaged with the pinion (2).

The pinion (2), connected to the solar (8) and integral, through the sliding sleeve (5), to the gear (7), transmits the motor rotation (M) to the planetary gears carrier (9) and thus to the output shaft (4) with ratio 1:1.



# 2.5.3 Gearbox in reduction (pic.3)

The sliding sleeve (5) engaged with the fixed crown (6) stops the rotation of the gear (7). The motor (M) through the pinion (2) and the solar gear (8), brings in rotation the planetary gears (10), which by rotating in the internal toothing of the locked gear (7) put the planetary gears carrier (9) in rotation and thus the output shaft with ratio in reduction.



| 2. | Setting | at. | work   |
|----|---------|-----|--------|
| ے. | Couring | 40  | #OI IV |

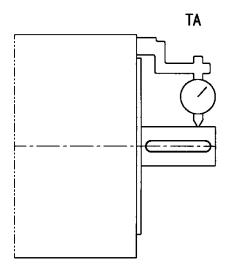
| Geart | OOX |
|-------|-----|
| Type  | Œ   |

Œ001-e

# 2.6 Main motor specifications

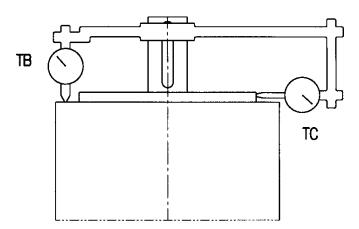
The motor which has to be applied to the gearbox has to be in accordance with the following specifications:

- Dimensions and power admitted by the gearbox
- Motor form B3/B5 for horizontal assembly positions (in order to reduce flexions and vibrations the motor has to be supported in the back side)
- Motor formV1/V3 for vertical assembly positions
- Motor without seal on the shaft
- Tolerances TA/TB/TC as per DIN 42955R
- Vibration level R.



### Tolerance DIN 43955R

| Dimension<br>motor | TA<br>mm | TB<br>mm | TC<br>mm |
|--------------------|----------|----------|----------|
| 112                | 0.025    | 0.050    | 0.050    |
| 132                | 0.025    | 0.063    | 0.063    |
| 160                | 0.030    | 0.063    | 0.063    |



Gearbox Type Œ

Œ001-e

### 2.7 Assembly positions and lubrications

The different assembling positions define also the ways of lubricating. The splash lubrication (standard) is foreseen only for horizontal assembling positions (OPP-OPD-OPS) and RPM limited as per data table 4.

Table 4

| SIZE | Maximum RPM input for splash lubrication |
|------|--|
| Œ 12 | 4500 RPM                                 |
| Œ 14 | 4000 RPM                                 |

For Horizontal assembling positions with higher RPM and for all vertical assembling positions the lubrication must be forced.

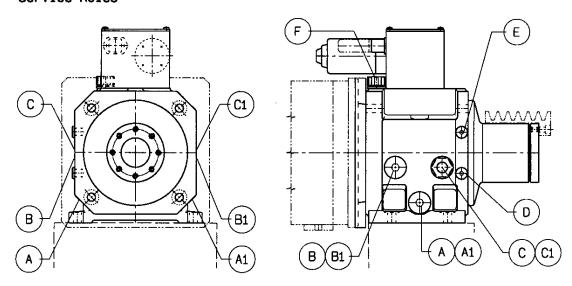
The use of the forced lubrication for any assembling position helps to take out the heat from the gearbox.

If the use foresees low temperature levels the forced lubrication could be integrated with the installation of a heat exchanger in order to cool the oil outside the gearbox.

To define better the measurements necessary to the loss of heat we suggest to analyse the problem during the test of the machine, because the heat which is generated it depends from the speed and the time of functioning.

The gearbox can stand, without troubles, temperatures up to 100° (oil90°)

### 2.7.1 Service holes



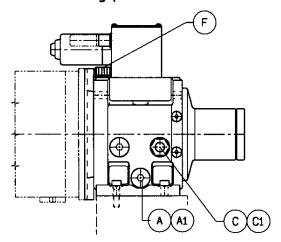
| SIZE | A/A1   | B/B1   | C/C1   | D      | E      | F      |
|------|--------|--------|--------|--------|--------|--------|
| Œ 12 | 3/4° G | 3/4° G | 3/4" G | 1/4° G | 1/4° G | 3/8° G |
| Œ 14 | 3/4" G | 3/4" G | 3/4" G | 1/4" G | 1/4° G | 3/8° G |

# Gearbox Type CE

Œ001-e

# 2.7.2 Horizontal assembling positions and splash lubrication

### - Assembling position OPP

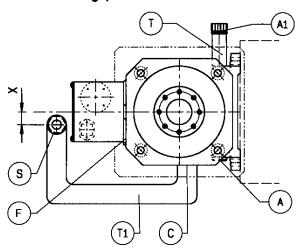


F = Oil loading plug/vent valve

C/C1 = Oil level

A/A1 = Oil drain plug

### - Assembling position OPD



A1 = Oil loading plug/vent valve

S = Oil level:it must be located
 at a dimension X and in communication
 with the hole C with proper
 pipes T1

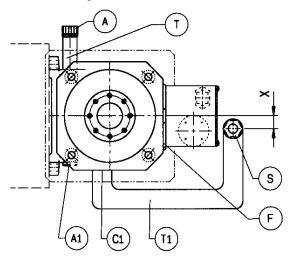
A = Oil drain plug

X = 0il level dimension (CE12 = 25 mm - CE14 = 40 mm)

F = To be plugged

T = Pipe

## - Assembling position OPS



A = Oil loading plug/vent valve

S = Oil level:it must be located
 at a dimension X and in communication
 with the hole C1 with proper
 pipes T1

A1 = Oil drain plug

X = Oil level dimension (OE12 = 25 mm - OE14 = 40 mm)

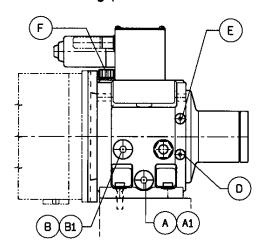
F = To be plugged

T = Pipe

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# 2.7.3 Horizontal assembling positions and forced lubrication

### - Assembling position OPP



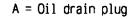
A/A1 = Oil drain plug

B/B1 = Forced lubrication input for elements in inlet using a choke (24) (0,4-0,5) lt/min

E = Forced lubrication for the central group (0,4-0,5 lt/min)

D =Forced lubrication for elements in outlet (0.4-0.5 lt/min)

F = Vent valve



A1 = Vent valve

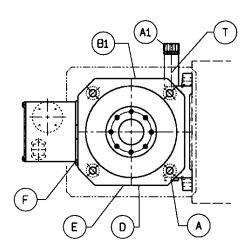
T = pipe

B1 = forced lubrication input for elements in inlet using a choke (24) (0.4-0.5 lt/min)

E = Forced lubrication for the central
 group (0.4/0.5 lt/min)

D = Forced lubrication for elements in outlet (0.4/0.5 lt/min)

F = To be plugged



в

A1 = Oil drain plug A = Vent valve

T = pipe

B = Forced lubrication input for elements in inlet using a choke (24) (0.4-0.5 lt/min)

E = Forced lubrication for the central group (0.4-0.5 litri/min)

D = Forced lubrication for elements in outlet (0.4-0.5 lt/min)

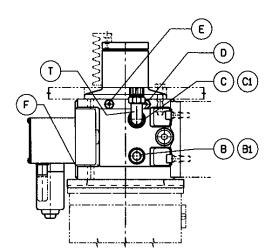
F = To be plugged

The pipe to be connected to the oil drain hole A/A1 has to have smooth internal surfaces in order to permit the oil to flow without difficulty and without creating an oil head in the gearbox (it is suggested to use a trasparent pipe with internal diameter of 20 mm minimum).



#### 2.7.4 Vertical assembling positions and forced lubrication

- Assembling position VFA/VPA (motor below and output to the high)



E = Forced lubrication for the central group (0.6-0.7 lt/min)

D = Forced lubrication for elements in outlet (0.6-0.7 lt/min)

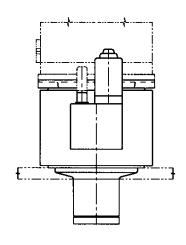
C/C1 = Vent valve

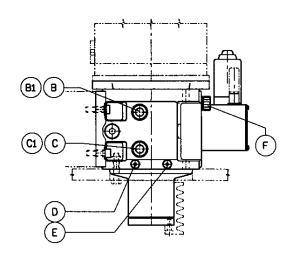
T = Pipe for the vent valve

B/B1 =Oil drain plug

F = To be plugged

- Assembling positions VPB/VFB (motor on the top and gearbox output below)





B = Forced lubrication for the elements in inlet with use of a choke (24) (0.6-0.7 lt/min)

B1 = Forced lubrication for the elements in inlet with use of a choke (24)  $\{0.6-0.7 \text{ lt/min}\}$ 

C/C1 = Oil drain plug

F = Vent valve

D = Oil suction in case of cooling circuit



The pipe to be connected to the oil drain hole B/B1-C/C1 has to have smooth internal surface in order to permit the oil to flow without difficulty an without creating an oil head in the gearbox (it is suggested to use a trasparent pipe with internal diameter of 20 mm. minimum).

|          |                         |  |        | M |
|----------|-------------------------|--|--------|---|
| JJD-4998 | Revision 01<br>May 1999 |  | Donato |   |

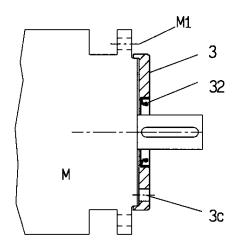
| Geart | XOC |
|-------|-----|
| Type  | Œ   |

Œ001-e

# 2.8 Gearbox motor connection and assembly

## 2.8.1 Motor flange assembly

The motor has to be assembled to the gearbox through a flange (3). For some motors with fixing holes diameter coincident with those of the gear box, the flange is only a centering element, therefore the flange has to be assembled on the motor as per pic. 4



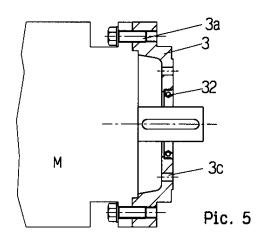
3 = Flange

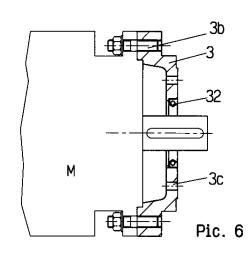
M = Motor

32 = Rotating seal

Pic. 4 M1 = Fixing holes

For motors with fixing holes diameter not coincident with those of the gearbox the flange has to be assembled to the motor as per indications in pic. 5 o pic. 6





3 = flange

3a = Screws

32 = Rotating seal

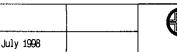
M = Motor

3b = Stud with its nut

3c = Drain hole

For horizontal assembling posizion the drain hole (3) on the flange(3c) has to be put on the botton







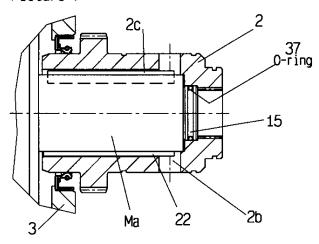
Gearbox Type Œ

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# 2.8.2 Assembly of the pinion to the shaft

Key the pinion (2) to the motor shaft (Ma) as per pictures 7, 8, or 8a

### Picture 7



Ma = motor shaft

2 = Pinion

3 = Flange

15 = Plug complete with its 0 ring

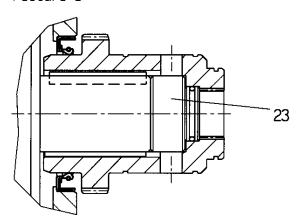
2b = Inspection and extraction holes

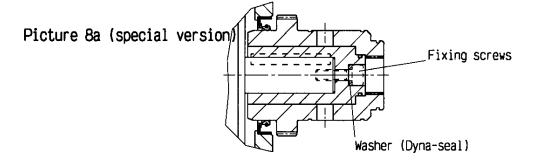
2c = Key

22 = Balancing key (use only for motors
 with balanced shaft with half key)

23 = Spacer (only by request)

# Picture 8





Verify through the holes (7b), that the plug (15) remains in its location



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|-----------|--|---------------------|-------|-------|-------|--|
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# Gearbox Type CE

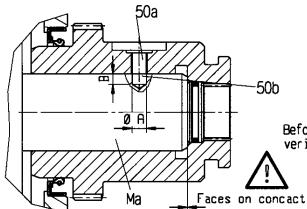
Œ001-e

### 2.8.3

With the pinion against the end of the motor shaft (pic 9), make a hole on the same (50b), as per data table 5.

(This operation has not be done with the special version in pic.8a-chapter 2.8.2.)

Pic. 9

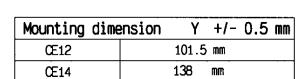


50a = Threaded hole

50b = Hole to be done on the motor shaft

Ma = Motor shaft

Before to drill the hole on the motor shaft verify the mounting dimension Y



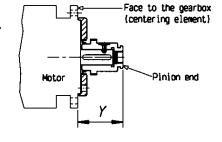
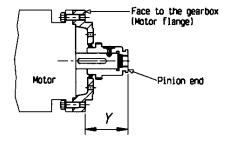


Table 5

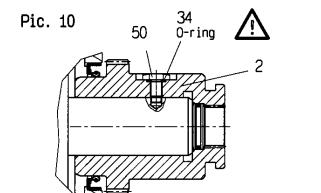
| Size | ØAmm | B mm |
|------|------|------|
| Œ12  | 6.75 | 4    |
| Œ14  | 8.5  | 5    |



Position the o-ring on the pinion spot-facing.

Tighten the locking screw and verify that the head is in contact with the pinion spot -facing





2 = Pinion

50 = Locking screw

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34 = 0-ring



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Gearbox Type CE

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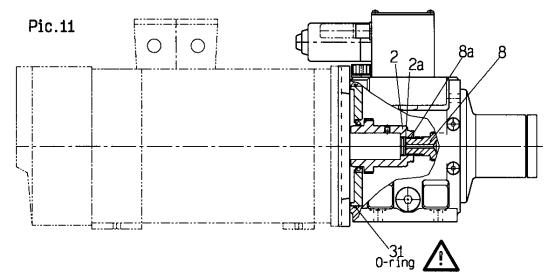
## 2.8.4 Gearbox assembly to the motor

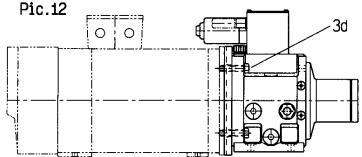
Verify the presence of the O-Ring (31).

Assembly the group motor-flange-pinion so that the extremity part of the pinion(2), which is broached, fits the correspondent part of the solar gear (8) (pic 11).

Fix everything through screw (pic12) or through studs and nuts (pic13).

For horizontal assembling positions, in order to reduce flexions and vibrations support the motor in the rear side.





2 = Pinion

2a = broached extremity

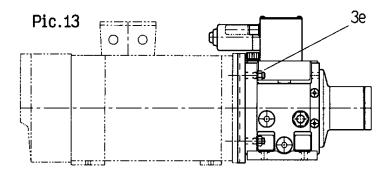
8 = solar gear

8a = Splined part

31 = 0-ring

3d = Screws

3e = Studs and nuts



It is suggested the utilisation of keys as per UNI 6741 (DIN 3113)

When the assembly is finished, control that the output shaft rotates free

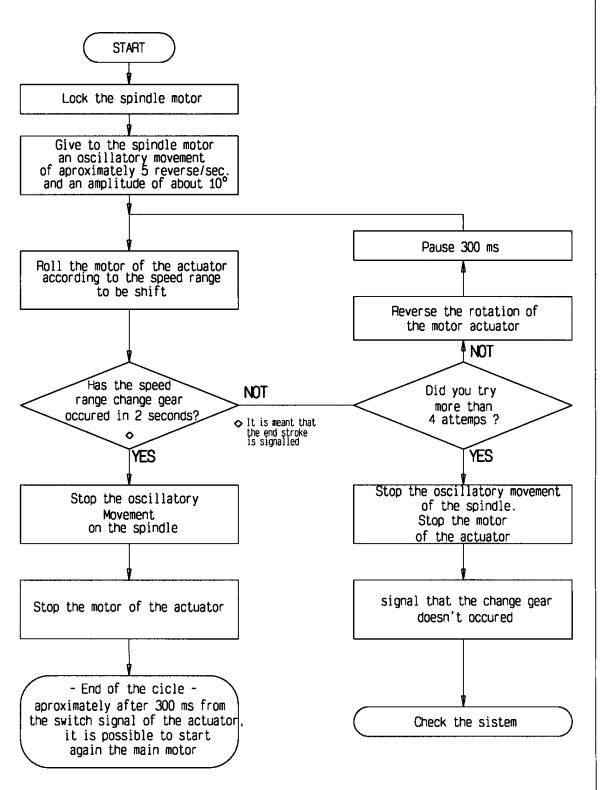




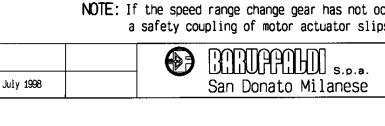
Gearbox 2 Setting at work Œ001-e Type Œ

#### 2.9 Electrical section

#### 2.9.1 Change gear flow cart



NOTE: If the speed range change gear has not occurred in the prefixed time a safety coupling of motor actuator slips.

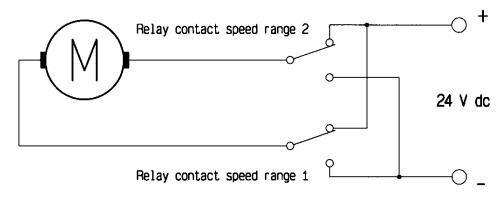


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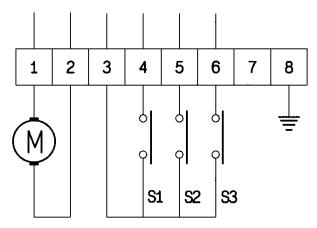
Œ001-e

### 2.9.2 Electrical wiring diagram

- Diagram of speed range change gear actuator: this solution avoid the lags due to the inertia of the motor actuator



- Connections on the connector (103) of the actuator (100)

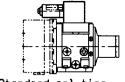


M = Motor actuator ( 24 Vcc 60 W )

S1 = limit switch range 1

S1 = limit switch range 2

S3 = free wheel position



Standard solution

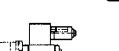
Actuator rotated of 180° respect standard solution

M = Motor actuator (24 Vcc 60 W)

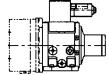
S1 = limit switch range 2

S2 = limit switch range 1

S3 = free wheel position



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# 3. Maintenance Gearbox Type CE CE001-e

### 3.1 Lubrication and control

The gearbox is supplied without oil: before working it is necessary to provide to fill the gearbox with oil.



The oil has to have an ISO VG 68 viscosity compatible with the seals and a good resistance against the corrosion and wear.

Tab.6 Table of lubricant

| Mobil                   | Agip   | Esso        | IP             | BP                  |
|-------------------------|--------|-------------|----------------|---------------------|
| DTE oil<br>Heavy Medium | 080 68 | TEPIESSO 68 | TONNA oil T 68 | ENERGOL<br>HLP D 68 |

### 3.1.1 Horizontal assembling position type OPP and standard lubrication

The necessary quantity of oil is indicated in tab.7

Tab.7

| Size | Oil quantity * |
|------|----------------|
| Œ12  | 1.1 l          |
| 0E14 | 3 1            |

These are just fiducial values, because it's necessary to check that the oil arrives ad the middle of the oil level light. It is suggested to control the oil when the gearbox is not in function and if necessary provide to refill the same.

Change the oil every 5000 hours and clean the magnetic plug which is on one of the discharge holes (A/A1).

### 3.1.2 Forced lubrication

The necessary oil flow is of 0,9-1,1 l/min. ( $20^{\circ}$  C) at 2-3 bar It is advised to use a oil-meter to secure the right flow Tank volume 25 litres.

Sistematically check the oil deflux. It must be regular not to increase the quantity of oil inside the gear box. (The oil level must not exceed the middle of the outlet hole).

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# 3.2 Failures research and repair

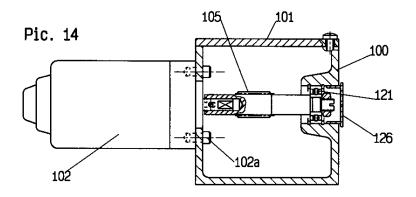
Each operation must be done with gearbox stopped and cold oil and surfaces



| Irregularity                                     | Possible cause  | Inspection   | Remedy  |
|--|---|--|---|
| The signal of change of the speed doesn't arrive | Microswitch 125<br>broken   | Verify manually that<br>the microswitch<br>changes status<br>(open-closed)   | Change the micro  |
|  | Worn micro push<br>road 125   | Verify that the micro is operated  | Change the micro  |
|  | Operating cam<br>backward   | by the cam 112   | Approach the cam to the micro see chapter 3.2.3.                |
|  | Actuator motor(102)<br>broken                                       | Verify the integrity of the motor  | Change the motor see chapter 3.2.1.                             |
|  | No imput<br>to the motor (102)                                      | Verify the correct<br>input to the motor<br>(24 V dc)  | Restore the electrical imput                                    |
| There is no                                      | During a change<br>the motor (M)<br>hunting<br>is missing           | Verify that<br>all phases of<br>diagram are<br>made 2.9.1  | Restore all as<br>per diagram at<br>chapter 2.9.1.              |
| change   | The torque of the safety coupling is not enought to make the change | With feeded motor (102<br>at (24 V dc) verify<br>that after a phase<br>of rotation of the gear<br>(106) follows a phase<br>at a slower speed | Restore the calibration of the safety joint; see chapter 3.2.2. |
|  | The torque of safety joint is too high                              |  |   |

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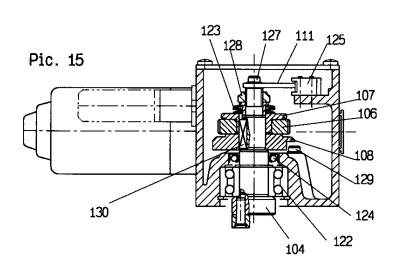
### 3.2.1 Change of the motor (102)



The motor (102) is fixed to the housing(100) with nº4 screws(102a). In order to get the screws it is necessary to remove:

- -The worm screw (105)
- -the gear (106)
- -and all necessary parts which can be found in Pic 14 and Pic 15.

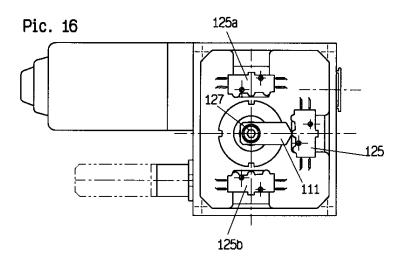
## 3.2.2 Safety joint calibration (belleville washers 123)



Feed the motor (102). Verify that the gear (106) at the beginning rotates. during the change, rotates quickly. At completed exchange the gear will be slowed down, therefore its movement will be slower (anyway it must slowly rotate till the motor is feeded). The calibration of the joint is made changing the pre-load of the belleville washers (123) (actuating the nut 128): -the screwing of the nut determines the torque of the joint;

-the unscrew of the nut determines the reduction of the joint's torque

## 3.2.3 Adjiustment of the cam which actuates the micro (111)



125 = Micro of neutral position

125a = Micro 1 st speed (1/1)

125b = Micro 2nd speed (1/4)

111 = Cam

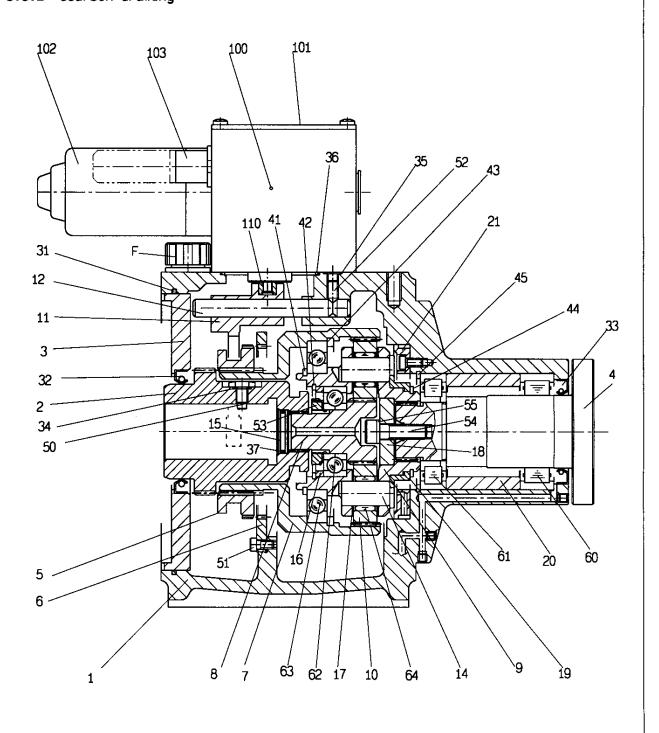
127 = Cam locking screw

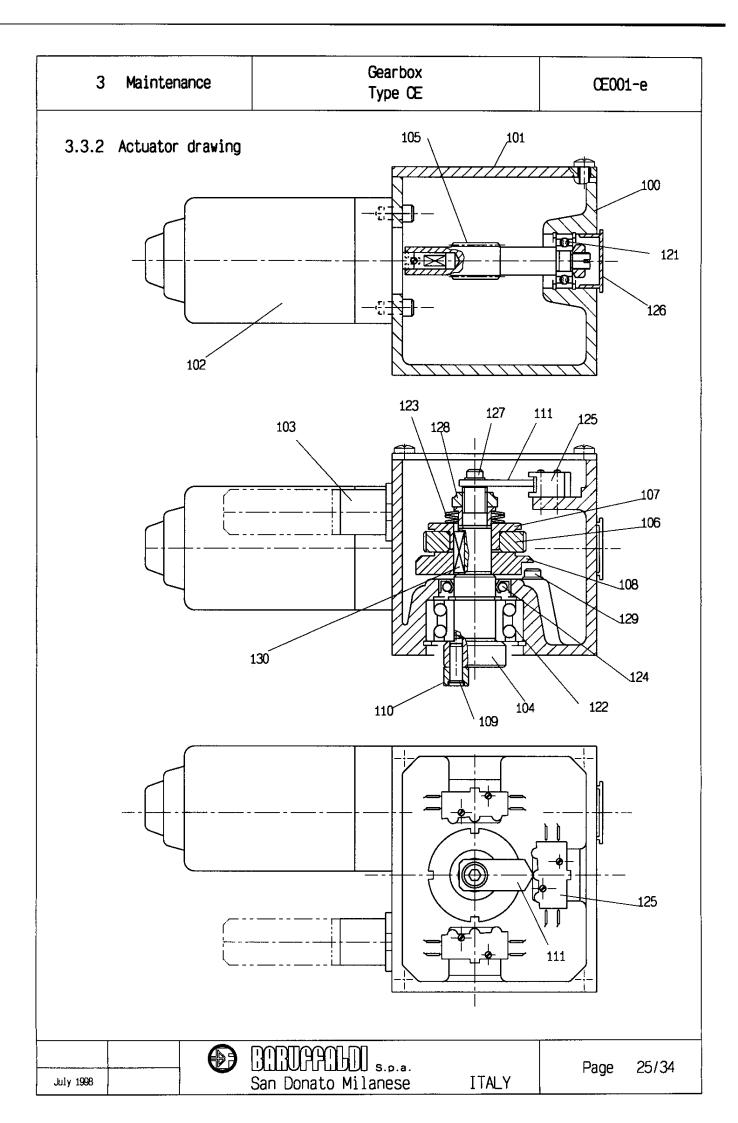
3 Maintenance Gearbox
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# 3.3 Assembly/disassembly

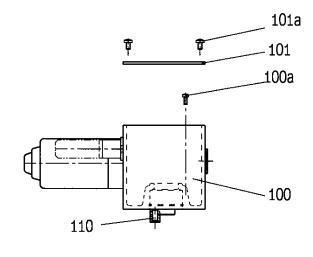
Any kind of disassembly operation has to be made with the gearbox is stillstand and with cold oil and cold surfaces

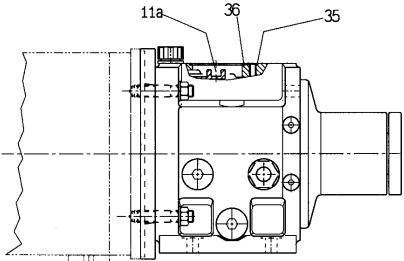
# 3.3.1 Gearbox-drawing





# 3.3.3 Disassembly/assembly of the actuator





### Disassembly phases

- remove the screws (101a) and the cover (101)
- Unscrew the 4 screws (100a).
- Remove the complete actuator (100).

### When re-assembling:

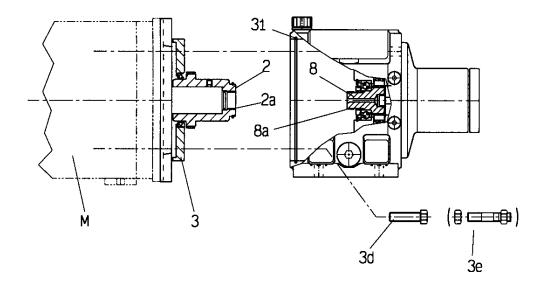
- Be sure to keep the O-rings (35) and (36)
- Engage the key(110) in the seat (11a) of the fork



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# 3.3.4 Disassembly /assembly of the motor flange



### Disassembly:

- remove the screw (3d) or the stud and nuts (3e)
- Take off the motor (M)-flange(3) unit

### Assembly

- Check the following points:
- The O-ring, must be in the right place
- The position of the fork and of the collar must be at slow speed (see chapter 2.5.3)

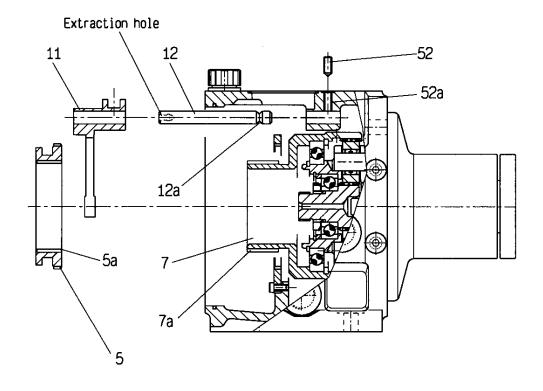
  Introduce the motor flange unit so that the broached end of the pinion fits the grooved part of the solar gear.

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# 3.3.5 Disassembly/assembly of the fork



### Disassembly

- unscrew the lock bolt (52)
- Take off the pivot (12)
- Remove the fork (11) and the collar (5)

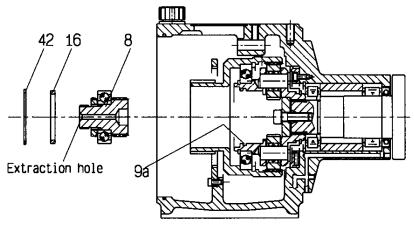
### Assembly:

- Insert the fork (11) on the collar (5). Engage the broached hole (5a) of the collar with the grooved part (7a) of the planetary gear (7)
- Insert the pivot (12) so that the groove (12a) reaches the hole (52a).
- -Lock completely the bolt (52) using loctite.

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## 3.3.6 Disassembly/assembly of the solar gear



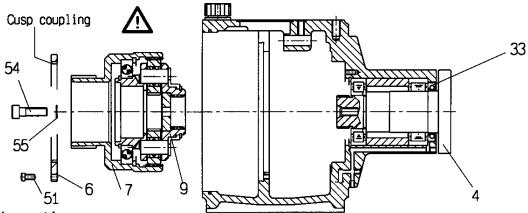
### Disassembly:

- Take off the circlip (42) and the spacer (16)
- Remove the solar gear (8) and the bearing

### Assembly:

- Check the circlip (42) fits the seat (9a) correctly

## 3.3.7 Disassembly/assembly of the planetary gear unit and of the driven shaft



### Disassembly:

- Release the screw (51).
- Take off the crown (6).
- Release the screw (54), take off the washer (55), take off the unit (7-9)
- Take off the driven shaft (4)

### Assembly:

- Be careful not to damage the shaft seal (33).
- Assembly correctly the crown: the cusp coupling must be turned towards the spindle motor (M)
- Lock completely the screw (54) using loctite 270 after removing,
   the grease from the screw and from the threaded hole







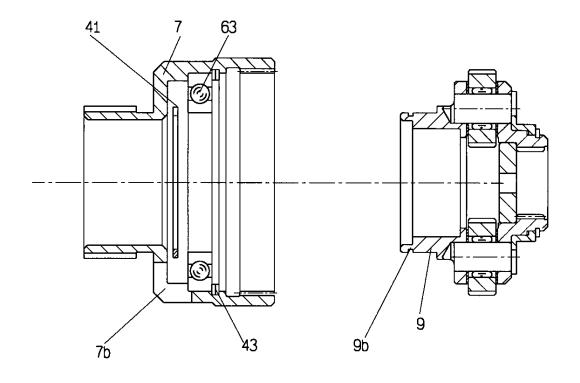
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# 3.3.8 Disassembly/assembly of the planetary gear



### Disassembly

- Trough the slots (7b), mark the position and then take off the circlip (41)
- Take off the planetary (7) gear toghether with the bearing (63) and the circlip (43).
- In case you have to disassemble the 2 circlips (43) mark the position between them and the planetary gear (7)

### Assembly:

- The circlip (41) must be placed in the space between the bearing (63) and the planetary gear shoulder (7).
- The circlip must be assembled (41) on the corresponding place of the planet-wheel carriage (9b).

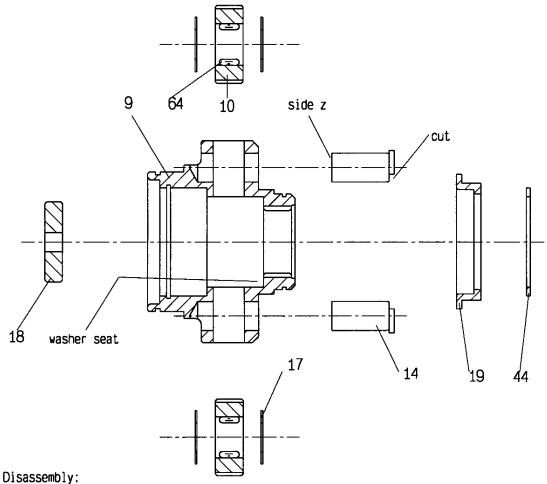
The circlips must be reassembled following the original position  $% \left( 1\right) =\left( 1\right) \left( 1\right) +\left( 1\right) \left( 1\right) \left( 1\right) +\left( 1\right) \left( 1\right)$ 



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#### 3.3.9 Disassembly/assembly of the planety gears



- Mark the position and then take off the circlip (44) and the spacer (19)
- Take off the pivot (14) from the planetary gears (9) by pushing them trough the z side
- Take off the planetary gears(10) the rollers (64) and the thrust blocks (17).
- Take off the washer (18).

### Assembly:

- before the assembly of the planetary gear, put the washer (18) in proper place
- Grease the roller using thick grease
- Turn the pivot(14) so that the cut on the head of the pivots must be towards the centre of the planetary gears (9).

Check the number of the rollers(64) the planetary gear. The number must be the same estabilished in chapters 3.4.1 and 3.4.2 (spare parts schedule)



The circlips must be reassembled following the original position



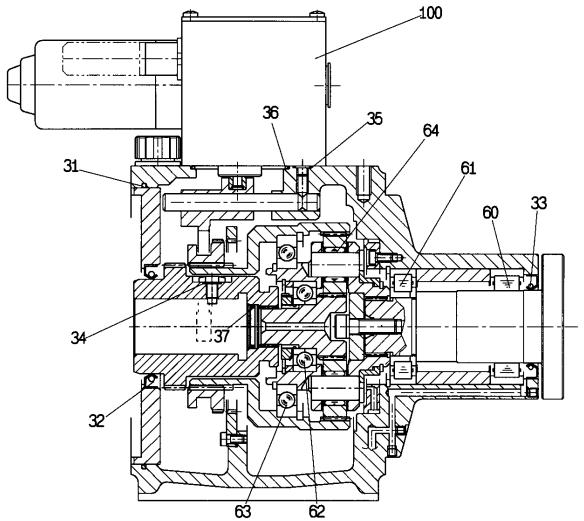
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3 Maintenance Gearbox
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# 3.4 spare-parts schedule

# 3.4.1 spare parts schedule OE 12

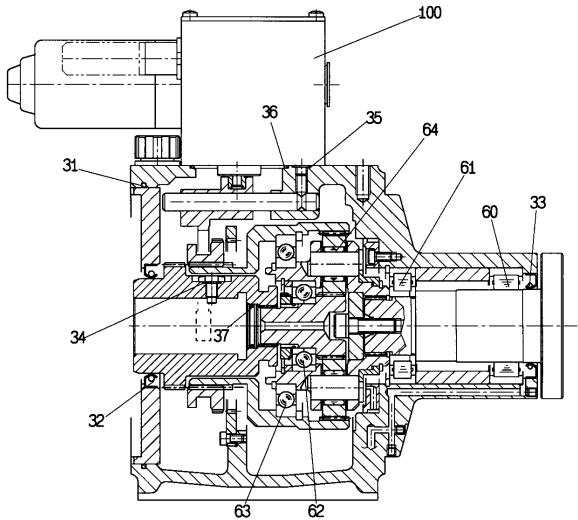


| NO  | Code           | Description | Туре                        | Q.ty |
|-----|----------------|-------------|-----------------------------|------|
| 31  | 999.223.02692  | 0-ring      | OR 264                      | 1    |
| 32  | 999.224.07318  | Shaft seal  | A 658510 Viton              | 1    |
| 33  | 999.224.07321  | Shaft seal  | A 50728 Viton               | 1    |
| 34  | 999.223.00792  | 0-ring      | OR 012                      | 1    |
| 35  | 999.223.00792  | 0-ring      | OR 012                      | 1    |
| 36  | 999.223.06431  | O-ring      | OR 144                      | 1    |
| 37  | 999.223.05287  | 0-ring      | OR 120                      | 1    |
| 60  | 999.148.06879  | Bearing     | NU 2208 ECP (no ralla int.) | 1    |
| 61  | 999.149.07569  | Bearing     | NUP 208 ECP                 | 1    |
| 62  | 999.149.07570  | Bearing     | QJ 206                      | 1    |
| 63  | 999.149.00867  | Bearing     | 16016                       | 1    |
| 64  | 999.149.07574  | Rollers     | NRA 3.5x15.8 G2 -3-5        | 18x4 |
| 100 | 23.0000.100.01 | Drive unit  |                             | 1    |

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# 3.4.2 Spare part schedule OE 14



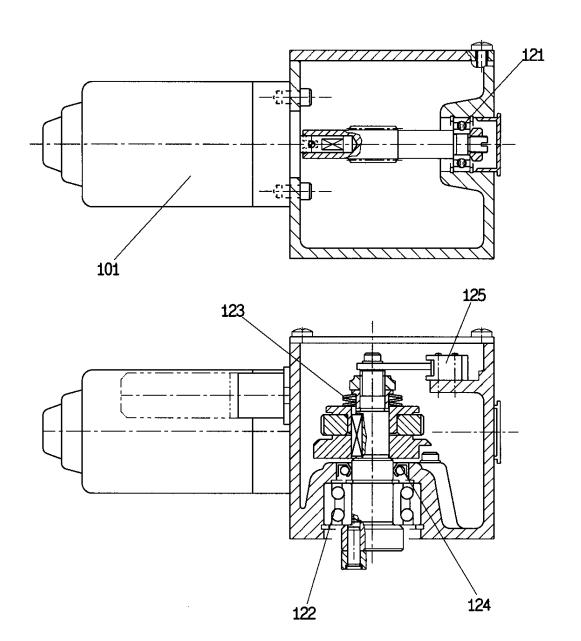
|     |                |             | <u> </u>                    |        |
|-----|----------------|-------------|-----------------------------|--------|
| NO  | Code           | Description | Туре                        | Q. tty |
| 31  | 999.223.02108  | 0-ring      | 0R 275                      | 1      |
| 32  | 999.263.07374  | Shaft seal  | A 8010010 Viton             | 1      |
| 33  | 999.224.07319  | Shaft seal  | A 709010 Viton              | 1      |
| 34  | 999.223.04988  | 0-ring      | 0R 013                      | 1      |
| 35  | 999.223.00792  | 0-ring      | 0R 012                      | 1      |
| 36  | 999.223.06431  | 0-ring      | OR 144                      | 1      |
| 37  | 999.223.05610  | 0-ring      | 0R 126                      | 1      |
| 60  | 999.149.07239  | Bearing     | NU 2211 EOP (no ralla int.) | 1      |
| 61  | 999.149.07572  | Bearing     | NUP 211 EOP                 | 1      |
| 62  | 999.149.07571  | Bearing     | QJ 208                      | 1      |
| 63  | 999.149.07272  | Bearing     | 16020                       | 1      |
| 64  | 999.149.07573  | Rollers     | NRA 5x23.8 G2 -3-5          | 16x4   |
| 100 | 23.0000.100.01 | Drive unit  |                             | 1      |

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Type CE

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# 3.4.3 Drive unit spare-parts schedule CE12 - CE14



| NO  | Code           | Description        | Type                                    | Q. tty |
|-----|----------------|--------------------|---|--------|
| 101 | 23.0000.114.01 | Engine             | 4-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1 | 1      |
| 121 | 999.148.07229  | Bearing            | 6000                                    | 1      |
| 122 | 999.149.03651  | Double bearing     | 3204                                    | 1      |
| 123 | 999.210.01933  | Belleville washers | 34x16.3x1.5                             | 3      |
| 124 | 999.226.07497  | Shaft seal         | A 20357                                 | 1      |
| 125 | 999.295.06893  | Micro switch       | 83106-0CW3 Crouzet                      | 3      |
|     |                |                    |   |        |

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